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Buckling analysis of CSCS and CSSS rectangular plates by split-deflection method

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Abstract—This paper presents buckling analysis of cscs and csss rectangular plates by split-deflection method. The assumption was that the deflection, w is split into w_x and w_y ; where the deflection was taken as the product of these two components in x and y directions. The study formulated the total potential energy function from principles of theory of elasticity. By direct variation, the energy function was minimized and equations for critical buckling loads were obtained. Two examples, one with edges 1 and 3 clamped, edges 2 and 4 simply supported and the other with edges 2, 3 and 4 simply supported and edge 1 clamped were used to test this method. The use of polynomial functions for both x and y components of deflection was adopted. Critical buckling loads (in non-dimensional forms) of the two examples for aspect ratios ranging from 1.0 to 2.0 (at increment of 0.1) were determined and compared with the values from a previous study. From the comparison, it was observed that the maximum percentage difference of 0.196 was recorded. The small values of percentage difference from this study show that this present method is sufficient and reliable for classical plate theory (CPT) buckling analysis of rectangular plates.

Index Terms—Critical buckling load, split-deflection, energy function, polynomial function.

I. INTRODUCTION

Classical plate theory (CPT) buckling analysis has dominated energy methods such as Raleigh, Ritz, Galerkin, minimum potential energy, etc [1-3]. Most of these energy methods are characterized by single deflection (un-separated) function. For instance, let us look at the energy function of work error method [3]:

$$\Pi = \frac{D}{2} \int_0^a \int_0^b \left(\frac{\partial^4 w}{\partial x^4} + 2 \frac{\partial^4 w}{\partial x^2 \partial y^2} + \frac{\partial^4 w}{\partial y^4} \right) \partial x \partial y - \frac{m \cdot \lambda^2}{2} \int_0^a \int_0^b w^2 \partial x \partial y$$

Most academic works on CPT analysis of rectangular plates as seen from the literature rely on this single orthogonal function [4-5], [1-2], [6-10] and [3]. Evidently, it can be affirmed that all energy functions currently in use in CPT buckling analysis are based on this single orthogonal deflection function. This means that none of the existing energy functions for buckling analysis in CPT has used a deflection function that is classically separated into two independent and distinct functions ($w = w_x \cdot w_y$) where w_x and w_y are both polynomial functions or w_x may be polynomial while w_y may be trigonometry [11]. The rationale for this adaptation is to help the analyst who might have difficulty in obtaining single orthogonal function for a plate of a particular boundary condition. In this case, the analyst who may have easy access to deflection equations for beams of any boundary condition can find this proposed method very handy [11].

II. ASSUMPTIONS

1. Basic- The hypothesis here is that the general deflection, w is split into w_x and w_y [11]. That is, the split-deflection function is given as:

$$w = w_x \cdot w_y \dots\dots\dots 1$$

Where the w_x and w_y components of the deflection are defined as:

$$w_x = \sqrt{A} \cdot h_1 \dots\dots\dots 2$$

$$w_y = \sqrt{A} \cdot h_2 \dots\dots\dots 3$$

$$w = \sqrt{A} \cdot h_1 \cdot \sqrt{A} \cdot h_2$$

Applying split-deflection and substituting equations (2) and (3) into equation (1) gives:

$$w = A h_1 h_2 \dots\dots\dots 4$$



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2. In-Plane Displacements- From the hypothesis that vertical shear strains are zero for classical plates and making use of split-deflection approach, we obtain:

$$u = -z \frac{dw}{dx} = -z \frac{dw_x}{dx} w_y \dots\dots 5$$

$$v = -z \frac{dw}{dy} = -z \frac{dw_y}{dy} w_x \dots\dots 6$$

3. Strain Deflection Relationship- Upon differentiating equations (5 and (6), the three in-plane strains of CPT are obtained:

$$\varepsilon_x = \frac{du}{dx} = -z \frac{d^2 w_x}{dx^2} w_y \dots\dots\dots 7$$

$$\varepsilon_y = \frac{dv}{dy} = -z \frac{d^2 w_y}{dy^2} w_x \dots\dots\dots 8$$

$$\gamma_{xy} = \frac{du}{dy} + \frac{dv}{dx} = -2z \frac{dw_x}{dx} \frac{dw_y}{dy} \dots\dots 9$$

4. Stress-Strain Relationship-The CPT constitutive equations for plane stress plates are:

$$\sigma_x = \frac{E}{1 - \mu^2} [\varepsilon_x + \mu \varepsilon_y] \dots\dots 10$$

$$\sigma_y = \frac{E}{1 - \mu^2} [\mu \varepsilon_x + \varepsilon_y] \dots\dots 11$$

$$\tau_{xy} = \frac{E(1 - \mu)}{2(1 - \mu^2)} \gamma_{xy} \dots\dots\dots 12$$

III. DERIVATION OF CRITICAL BUCKLING LOAD EQUATION USING SPLIT DEFLECTION METHOD

1. Stress-Deflection Relationship- When equations (7), (8) and (9) are substituted into equations (10), (11) and (12) as appropriate, the split-deflection stress-deflection equations are obtained as:

$$\sigma_x = \frac{-Ez}{1 - \mu^2} \left[\frac{d^2 w_x}{dx^2} w_y + \mu \frac{d^2 w_y}{dy^2} w_x \right] \dots\dots\dots 13$$

$$\sigma_y = \frac{-Ez}{1 - \mu^2} \left[\mu \frac{d^2 w_x}{dx^2} w_y + \frac{d^2 w_y}{dy^2} w_x \right] \dots\dots\dots 14$$

$$\tau_{xy} = \frac{-Ez(1 - \mu)}{(1 - \mu^2)} \frac{dw_x}{dx} \frac{dw_y}{dy} \dots\dots\dots 15$$

2. Total Potential Energy- Strain energy is commonly defined as:

$$U = \frac{1}{2} \int_x \int_y \left[\int_{-\frac{t}{2}}^{\frac{t}{2}} [\sigma_x \varepsilon_x + \sigma_y \varepsilon_y + \tau_{xy} \gamma_{xy}] dz \right] dx dy \dots\dots 16$$

For buckling analysis, the external work in x direction is given as:



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$$V = \frac{N_x}{2} \int_x \int_y \frac{d^2 w}{dx^2} w \cdot dx \cdot dy$$

That is,

$$V = \frac{N_x}{2} \int_x \frac{d^2 w_x}{dx^2} w_x \cdot dx \int_y w_y^2 \cdot dy \dots\dots \quad 17$$

When equations (4) to (6) are substituted into equation (7) we obtain strain energy – deflection equation form as:

$$U = \frac{D}{2} \left[\int_x \frac{d^4 w_x}{dx^4} w_x \cdot dx \int_y w_y^2 \cdot dy \right] + \frac{2D}{2} \left[\int_x \frac{d^2 w_x}{dx^2} w_x \cdot dx \int_y \frac{d^2 w_y}{dy^2} w_y \cdot dy \right] + \frac{D}{2} \left[\int_x w_x^2 \cdot dx \int_y \frac{d^4 w_y}{dy^4} w_y \cdot dy \right] \dots\dots\dots \quad 18$$

Adding equations (17) and (18) give the total potential energy function as:

$$\Pi = \frac{D}{2} \left[\int_x \frac{d^4 w_x}{dx^4} w_x \cdot dx \int_y w_y^2 \cdot dy \right] + \frac{2D}{2} \left[\int_x \frac{d^2 w_x}{dx^2} w_x \cdot dx \int_y \frac{d^2 w_y}{dy^2} w_y \cdot dy \right] + \frac{D}{2} \left[\int_x w_x^2 \cdot dx \int_y \frac{d^4 w_y}{dy^4} w_y \cdot dy \right] + \frac{N_x}{2} \int_x \frac{d^2 w_x}{dx^2} w_x \cdot dx \int_y w_y^2 \cdot dy \dots\dots \quad 19$$

When equations (2) and (3) are substituted into equation (19) we obtain:

$$\Pi = \frac{A^2 D}{2} \left[\int_x \frac{d^4 h_1}{dx^4} h_1 \cdot dx \int_y h_2^2 \cdot dy \right] + \frac{2A^2 D}{2} \left[\int_x \frac{d^2 h_1}{dx^2} h_1 \cdot dx \int_y \frac{d^2 h_2}{dy^2} h_2 \cdot dy \right] + \frac{A^2 D}{2} \left[\int_x h_1^2 \cdot dx \int_y \frac{d^4 h_2}{dy^4} h_2 \cdot dy \right] + \frac{N_x}{2} \int_x \frac{d^2 w_x}{dx^2} w_x \cdot dx \int_y w_y^2 \cdot dy \dots \quad 20$$

Using non-dimensional form of axes R and Q, equation (20) shall be written as:

$$x = aR \dots\dots\dots \quad 21$$

$$y = aQ \dots\dots\dots \quad 22$$

$$P = \frac{b}{a} \dots\dots\dots \quad 23$$

Here a, b and P are the plate lengths in x and y axes and long span- short span aspect ratio respectively. When equations (21-23) are substituted into equation (20) we obtain:

$$\Pi = \frac{abA^2 D}{2a^4} \left[\int_0^1 \frac{d^4 h_1}{dR^4} h_1 \cdot dR \int_0^1 h_2^2 \cdot dQ \right] + 2 \frac{abA^2 D}{2a^4 P^2} \left[\int_0^1 \frac{d^2 h_1}{dR^2} h_1 \cdot dR \int_0^1 \frac{d^2 h_2}{dQ^2} h_2 \cdot dQ \right] + \frac{abA^2 D}{2a^4 P^4} \left[\int_0^1 h_1^2 \cdot dR \int_0^1 \frac{d^4 h_2}{dQ^4} h_2 \cdot dQ \right] + \frac{abA^2 N_x}{2a^2} \int_x \frac{d^2 h_1}{dR^2} h_1 \cdot dR \int_y h_2^2 \cdot dQ \dots\dots\dots \quad 24$$

3. Direct Variation of Total Potential Energy- For direct variation, equation (24) shall be differentiated with respect to the deflection coefficient, A and the outcome is:

$$\frac{d\Pi}{dA} = \frac{AD}{a^4} \left[\int_0^1 \frac{d^4 h_1}{dR^4} h_1 \cdot dR \int_0^1 h_2^2 \cdot dQ \right] + 2 \frac{AD}{a^4 P^2} \left[\int_0^1 \frac{d^2 h_1}{dR^2} h_1 \cdot dR \int_0^1 \frac{d^2 h_2}{dQ^2} h_2 \cdot dQ \right]$$



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$$+ \frac{AD}{a^4 P^4} \left[\int_0^1 h_1^2 dR \int_0^1 \frac{d^4 h_2}{dQ^4} h_2 dQ \right] + \frac{abAN_x}{a^2} \int_x \frac{d^2 h_1}{dR^2} h_1 dR \int_y h_2^2 dQ = 0$$

That is

$$\frac{D}{a^4} \left[\int_0^1 \frac{d^4 h_1}{dR^4} h_1 dR \int_0^1 h_2^2 dQ \right] + 2 \frac{D}{a^4 P^2} + \frac{D}{a^4 P^4} \left[\int_0^1 h_1^2 dR \int_0^1 \frac{d^4 h_2}{dQ^4} h_2 dQ \right] + \frac{abAN_x}{a^2} \int_x \frac{d^2 h_1}{dR^2} h_1 dR \int_y h_2^2 dQ \dots\dots\dots 25$$

Equation (25) is the direct governing equation of rectangular plate under buckling using work-error.

Rearranging equation (25) and making the critical buckling load, N_x the subject of the equation gives:

$$N_x = \left(\frac{p^2 k_x + 2k_{xy} + \frac{k_y}{p^2}}{k_{N_x}} \right) * \frac{D}{b^2} \dots\dots\dots 26$$

Where

$$k_x = \int_0^1 \frac{d^4 h_1}{dR^4} h_1 dR \int_0^1 h_2^2 dQ \dots\dots\dots 27$$

$$k_{xy} = \int_0^1 \frac{d^2 h_1}{dR^2} h_1 dR \int_0^1 \frac{d^2 h_2}{dQ^2} h_2 dQ \dots\dots\dots 28$$

$$k_y = \int_0^1 h_1^2 dR \int_0^1 \frac{d^4 h_2}{dQ^4} h_2 dQ \dots\dots\dots 29$$

and

$$k_{N_x} = \int_x \frac{d^2 h_1}{dR^2} h_1 dR \int_y h_2^2 dQ \dots\dots\dots 30$$

IV. APPLICATION

Analysis of a classical rectangular thin isotropic plate with:

- 1) Edges 1 & 3 clamped; edges 2 & 4 simply supported using polynomial functions respectively for w_x and w_y .
- 2) Edge 1 clamped, edges 2, 3 and 4 simply supported using only polynomial function for both w_x and w_y

1. Edges 1 & 3 clamped; edges 2 & 4 simply supported rectangular plate

The deflection equation, w and shape function [3] for CSCS rectangular plates are

$$w = A (R - 2R^3 + R^4)(Q^2 - 2Q^3 + Q^4) \dots\dots\dots 31$$

Using split-deflection approach, we have

$$w_x = \sqrt{A} (R - 2R^3 + R^4) \dots\dots\dots 32$$

$$w_y = \sqrt{A} (Q^2 - 2Q^3 + Q^4) \dots\dots\dots 33$$

From equations (32) and (33), shape (profile) functions h_1 and h_2 are:

$$h_1 = R - 2R^3 + R^4 \dots\dots\dots 34$$

$$h_2 = Q^2 - 2Q^3 + Q^4 \dots\dots\dots 35$$

When we integrate these profile functions, we obtain:



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$$\int_0^1 h_1^2 dR = \int_0^1 (R^2 - 4R^4 + 2R^5 + 4R^6 - 4R^7 + R^8) dR$$

$$\frac{R^3}{3} - \frac{4R^5}{5} + \frac{2R^6}{6} + \frac{4R^7}{7} - \frac{4R^8}{8} + \frac{R^9}{9}$$

$$\frac{1}{3} - \frac{4}{5} + \frac{2}{6} + \frac{4}{7} - \frac{4}{8} + \frac{1}{9} = \frac{31}{630}$$

$$\text{and } \int_0^1 h_2^2 dQ = \int_0^1 (Q^4 - 4Q^5 + 6Q^6 - 4Q^7 + Q^8) dQ$$

$$= \frac{Q^5}{5} - \frac{4Q^6}{6} + \frac{6Q^7}{7} - \frac{4Q^8}{8} + \frac{Q^9}{9} \Big|_0^1$$

$$\frac{1}{5} - \frac{4}{6} + \frac{6}{7} - \frac{4}{8} + \frac{1}{9} = \frac{1}{630}$$

Similar procedure was adopted to obtain the values

$$\int_0^1 \frac{d^4 h_1}{dR^4} h_1 dR = \frac{24}{5} \text{ and } \int_0^1 \frac{d^4 h_2}{dQ^4} h_2 dQ = \frac{4}{5}$$

$$\int_0^1 \frac{d^2 h_1}{dR^2} h_1 dR = \frac{17}{35} \text{ and } \int_0^1 \frac{d^2 h_2}{dQ^2} h_2 dQ = \frac{2}{105}$$

$$k_x = \left(\frac{24}{5}\right) \left(\frac{1}{630}\right) = \frac{4}{525} \dots\dots 36$$

$$k_{xy} = \left(\frac{17}{35}\right) \left(\frac{2}{105}\right) = \frac{34}{3675} \dots\dots\dots 37$$

$$k_y = \left(\frac{31}{630}\right) \left(\frac{4}{5}\right) = \frac{123}{3125} \dots\dots 38$$

and

$$k_{N_x} = \left(\frac{17}{35}\right) \left(\frac{1}{630}\right) = \frac{17}{22050} \dots 39$$

Substituting equations (36-39) into equation (26) gives

$$N_x = \left(\frac{0.007617p^2 + 2 * \left(\frac{34}{3675} \right) + \frac{0.03936}{p^2}}{0.0007708} \right) * \frac{D}{b^2}$$

That is

$$N_x = \left(9.88194P^2 + 24.00545 + \frac{51.06383}{P^2} \right) * \frac{D}{b^2} \dots\dots\dots 40$$



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2. Edge 1 clamped & edges 2, 3 & 4 simply supported rectangular plate

The deflection equation, w and the shape function [3] H for CSSS rectangular plates are

$$w = A (R - 2R^3 + R^4)(1.5Q^2 - 2.5Q^3 + Q^4) \dots \quad 41$$

Using split-deflection approach, we have

$$w_x = \sqrt{A} (R - 2R^3 + R^4) \dots \dots \dots \quad 42$$

$$w_y = \sqrt{A} (1.5Q^2 - 2.5Q^3 + Q^4) \dots \dots \dots \quad 43$$

From equations (42) and (43), h_1 and h_2 are:

$$h_1 = R - 2R^3 + R^4 \dots \dots \dots \quad 44$$

$$h_2 = 1.5Q^2 - 2.5Q^3 + Q^4 \dots \dots \dots \quad 45$$

With these equations, we obtain:

$$\int_0^1 h_1^2 dR = \int_0^1 (R - 2R^3 + R^4)^2 dR = \int_0^1 (R^2 - 4R^4 + 2R^5 + 4R^6 - 4R^7 + R^8) dR$$

$$= \frac{R^3}{3} - \frac{4R^5}{5} + \frac{2R^6}{6} + \frac{4R^7}{7} - \frac{4R^8}{8} + \frac{R^9}{9}$$

$$\frac{1}{3} - \frac{4}{5} + \frac{2}{6} + \frac{4}{7} - \frac{4}{8} + \frac{1}{9} = \left(\frac{31}{630}\right)$$

and

$$\int_0^1 h_2^2 dQ = \int_0^1 (1.5Q^2 - 2.5Q^3 + Q^4)^2 = \int_0^1 (2.25Q^4 - 7.5Q^5 + 9.25Q^6 - 5Q^7 + Q^8) dQ$$

$$\left(\frac{2.25Q^5}{5} - \frac{7.5Q^6}{6} + \frac{9.25Q^7}{7} - \frac{5Q^8}{8} + \frac{Q^9}{9}\right)\Bigg|_0^1$$

$$\frac{2.25}{5} - \frac{7.5}{6} + \frac{9.25}{7} - \frac{5}{8} + \frac{1}{9} = 19/2520$$

$$\int_0^1 \frac{d^4 h_1}{dR^4} h_1 dR = 4.8 \text{ and } \int_0^1 \frac{d^4 h_2}{dQ^4} h_2 dQ = \frac{9}{5}$$

$$\int_0^1 \frac{d^2 h_1}{dR^2} h_1 dR = \frac{17}{35} \text{ and } \int_0^1 \frac{d^2 h_2}{dQ^2} h_2 dQ = \frac{3}{35}$$

$$k_x = (4.8) \left(\frac{19}{2520}\right) = \frac{19}{525} \dots \dots \quad 46$$

$$k_{xy} = \left(\frac{17}{35}\right) \left(\frac{3}{35}\right) = \frac{51}{1225} \dots \dots \quad 47$$



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$$k_y = \left(\frac{31}{630}\right)(1.8) = \frac{279}{1350} \dots\dots 48$$

$$k_{N_x} = \left(\frac{17}{35}\right)\left(\frac{19}{2500}\right) = \frac{323}{88200} \dots\dots 49$$

Substituting equations (46-49) into equation (26) gives

$$N_x = \left(\frac{0.03619p^2 + 2 * 0.041633 + \frac{0.088571}{p^2}}{0.0036621}\right) * \frac{D}{b^2}$$

That is

$$N_x = \left(9.88231P^2 + 22.73723 + \frac{24.1859}{P^2}\right) * \frac{D}{b^2} \dots\dots\dots 50$$

V. RESULTS

The non-dimensional form of the critical buckling loads for different aspect ratios for cscs and csss plates are shown on tables 1 and 2. Figures 1 and 2 present same result in graphical form.

Table 1: Non-dimensional form of critical buckling load of CSCS isotropic thin plate

Aspect ratio, P	Critical buckling load, $N_x \left(\frac{D}{a^2}\right)$		Percentage difference
	Present	Past [3]	
1	84.95	85.06494	0.135
1.1	78.16	78.27207	0.143
1.2	73.70	73.80192	0.138
1.3	70.92	71.0267	0.150
1.4	69.426	69.53446	0.1560
1.5	68.933	69.04582	0.163
1.6	69.248	69.36585	0.170
1.7	70.231	70.35524	0.176
1.8	71.780	71.91225	0.184
1.9	73.821	73.96119	0.1895
2.0	76.295	76.44481	0.1960

$$N_x = \left(9.88P^2 + 24.01 + \frac{51.06}{P^2}\right) \cdot \frac{D}{b^2}$$

In the case of CSCS thin plates, that is table 1, for the aspect ratio of 1.0, the buckling load was 84.95. For the aspect ratio of 2.0, the buckling load was 76.295. From the table; it can be observed that as the aspect ratio increased from 1.0 to 2.0, the buckling load decreased from 84.95 to 76.295. Therefore, for an increment of 1.0 (1.0-2.0) aspect ratio, there was a decrease of 8.66 non-dimensional form of buckling load.

Table 2 shows results for CSSS Isotropic Thin Plates. For the aspect ratio of 1.0, the buckling load was 56.81. It decreased to a point corresponding to the aspect ratio of 1.5. It gradually increased again at aspect ratio of 2.0. Therefore, for an aspect ratio of 1.0 to 1.5, there was a decrease of 1.089 non-dimensional form of buckling load. For the aspect ratio of 1.6 to 2.0, there was an increase of 10.826 non-dimensional form of buckling load. This variation in buckling load can be attributed to the plate boundary configuration and restraint conditions.



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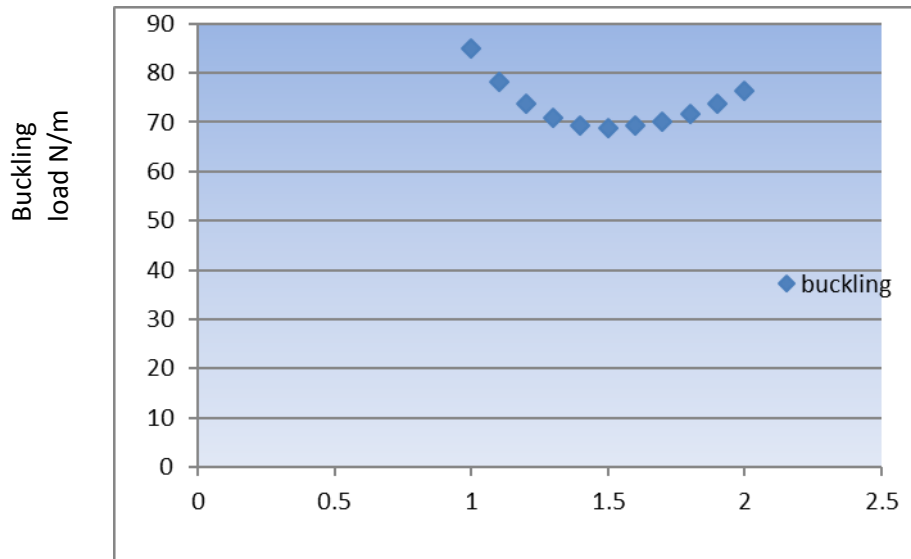


Fig 1: The Graph of Non-Dimensional Buckling Load against Aspect Ratio (CSCS plate).

Table 2: Non-dimensional form of critical buckling load of CSSS isotropic thin plate

Aspect ratio, P	Critical buckling load, $N_x \left(\frac{D}{\sigma^2} \right)$		Percentage difference
	Present	Past [3]	
1	56.810	56.80234	0.014
1.1	54.687	54.68031	0.013
1.2	53.766	53.76084	0.018
1.3	53.751	53.74698	0.007
1.4	54.447	54.44388	0.006
1.5	55.721	55.71938	0.004
1.6	57.482	57.4813	0.002
1.7	59.663	59.66373	0.002
1.8	62.217	62.21855	0.003
1.9	65.108	65.10996	0.003
2.0	68.308	68.31088	0.004

$$N_x = \left(9.88P^2 + 22.74 + \frac{24.19}{P^2} \right) \cdot \frac{D}{b^2}$$

From the graph of Figure 1.0, the buckling load, N_x graph becomes parabolic at an aspect ratio of 1.5. Obviously, this could be attributed to the boundary condition (restraint) of the plate. Which means for different plate geometry/configuration, the buckling load, (N_x) vis-a-viz, the aspect ratio changes.



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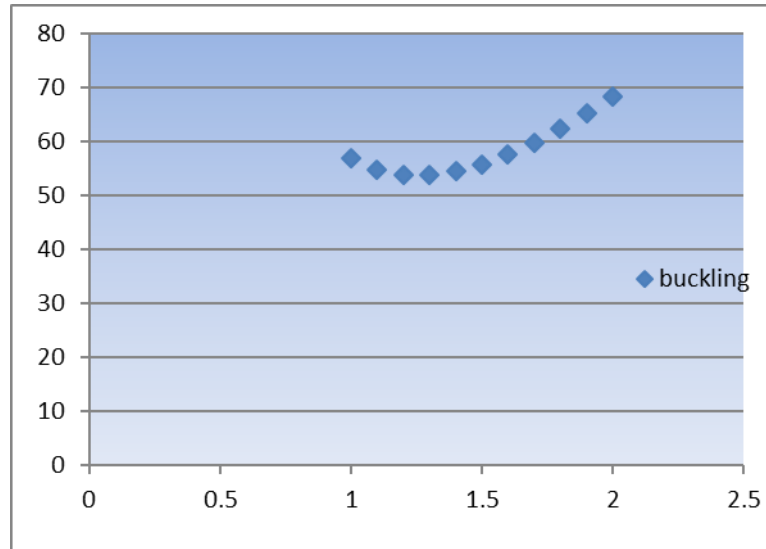


Fig 2: The Graph of non-dimensional Buckling Load against Aspect Ratio (CSSS plate)

In Figure 2.0, at the origin of the curve, the aspect ratio was 1.0 with non-dimensional buckling load of 56.810. The graph descended gradually to non-dimensional buckling load of 55.721. This corresponded to an aspect ratio of 1.5. The descent of the curve was very steep. The ascent corresponds to the aspect ratio of 1.6 and continues to 2.0 with non-dimensional buckling load of 68.308. This variation in buckling load can be attributed to the plate boundary configuration and restraint conditions.

VI. CONCLUSIONS AND RECOMMENDATIONS

A critical examination of the tables reveals that the maximum percentage difference between the values from the present study and those from Ibearugbulem [3] is 0.196. This value of the difference may be due to round off error. Statistically, the implication is, that no difference exists between the two sets of values. Thus, one can infer that the procedure, the profile functions and the energy functions formulated in this present study are reliable and sufficient in CPT buckling analysis of rectangular plates. From the findings of this study, this method is recommended for stability analysis of CPT plates [11]. A further study for use of the present method in refined plate theory analysis (RPT) is also recommended. This study therefore developed an alternative equation option to the single orthogonal deflection equations already in use in plates analysis. It successfully applied the split-deflection method in the analysis of thin isotropic rectangular plates- that is a new plate buckling concept where a rectangular plate is split into two independent and distinct components x and y, where the deflection of the rectangular plate becomes the product of these two components x and y ($w = w_x * w_y$).

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