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Stability Analysis of Mathematical Syn-Ecological Model Comprising of Prey-Predator, Host-Commensal, Mutualism and Neutral Pairs-IV (One of the Four Species are Washed out States)

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Abstract - This investigation deals with a mathematical model of a four species (S₁, S₂, S₃ and S₄) Syn-Ecological system (one of the four species are washed out states). S₂ is a predator surviving on the prey S₁. The predator S₂ is a commensal to the host S₃. The pairs S₂ and S₄, S₁ and S₃ are neutral. The mathematical model equations characterizing the syn-ecosystem constitute a set of four first order non-linear coupled differential equations. There are in all sixteen equilibrium points. Criteria for the stability of four of the sixteen equilibrium points: One of the four species are washed out states only are established in this paper. The linearized equations for the perturbations over the equilibrium points are analyzed to establish the criteria for stability and the trajectories illustrated.

I. INTRODUCTION

Mathematical modeling is an important interdisciplinary activity which involves the study of some aspects of diverse disciplines. Biology, Epidemiology, Physiology, Ecology, Immunology, Bio-economics, Genetics, Pharmacokinetics are some of those disciplines. This mathematical modeling has raised to the zenith in recent years and spread to all branches of life and drew the attention of every one. Mathematical modeling of ecosystems was initiated by Lotka [9] and by Volterra [18]. The general concept of modeling has been presented in the treatises of Meyer [11], Cushing [4], Paul Colinvaux [11], Freedman [5], Kapur [6, 7]. The ecological interactions can be broadly classified as Prey-Predation, Competition, and Mutualism and so on. N.C. Srinivas [17] studied the competitive eco-systems of two species and three species with regard to limited and unlimited resources. Later, Lakshmi Narayan [8] has investigated the two species prey-predator models. Stability analysis of competitive species was carried out by Archana Reddy [3] while Acharyulu [1, 2] investigated Ammensalism between two species. Recently local stability analysis for a two-species ecological mutualism model has been investigated by present author et al [12, 13, 14, 15, 16]. Example for S₁, S₂, S₃ and S₄ are Insects, Insectivorous Plants (nephantis, drosera etc.), VAM associated with the plant roots, Soil bacteria respectively.

II. BASIC EQUATIONS

The model equations for a four species multi-system are given by a set of four non-linear ordinary differential equations as

(i) For S₁: The Prey of S₁ and Neutral to S₃

$$\frac{dN_1}{dt} = a_1 N_1 - a_{11} N_1^2 - a_{12} N_1 N_2 \quad \dots (2.1)$$

(ii) For S₂: The Predator surviving on S₁ and Commensal to S₃

$$\frac{dN_2}{dt} = a_2 N_2 - a_{22} N_2^2 + a_{21} N_2 N_1 + a_{23} N_2 N_3 \quad \dots (2.2)$$

(iii) For S₃: The Host of S₂ and Mutual to S₄

$$\frac{dN_3}{dt} = a_3 N_3 - a_{33} N_3^2 + a_{34} N_3 N_4 \quad \dots (2.3)$$

(iv) For S₄: Mutual to S₃ and Neutral to S₂



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$$\frac{dN_4}{dt} = a_4 N_4 - a_{44} N_4^2 + a_{43} N_4 N_3 \quad \dots (2.4)$$

with the following notation.

$N_i(t)$: Population strengths of the species S_i at time t , $i=1, 2, 3, 4$.

a_i : The natural growth rates of S_i , $i = 1,2,3,4$

a_{12}, a_{21} : Interaction (Prey-Predator) coefficients of S_1 due to S_2 and S_2 due to S_1

a_{13} : Coefficient for commensal for S_1 due to the Host S_3

a_{34}, a_{43} : Mutually interaction between S_3 and S_4

$K_i: \frac{a_i}{a_{ii}}$: Carrying capacities of S_i , $i=1, 2, 3, 4$.

Further the variables N_1, N_2, N_3, N_4 are non-negative and the model parameters $a_1, a_2, a_3, a_4; a_{11}, a_{22}, a_{33}, a_{44}; a_{12}, a_{21}, a_{13}, a_{24}$ are assumed to be non-negative constants.

III. EQUILIBRIUM STATES

The system under investigation has sixteen equilibrium states defined by

$$\frac{dN_i}{dt} = 0, \quad i = 1, 2, 3, 4 \quad \dots (3.1)$$

are given in the following table.

I. Fully washed out state:

$$E_1: \quad \bar{N}_1 = 0, \bar{N}_2 = 0, \bar{N}_3 = 0, \bar{N}_4 = 0$$

II. States in which three of the four species are washed out and fourth is surviving

$$E_2: \quad \bar{N}_1 = 0, \bar{N}_2 = 0, \bar{N}_3 = 0, \bar{N}_4 = \frac{a_4}{a_{44}}$$

$$E_3: \quad \bar{N}_1 = 0, \bar{N}_2 = 0, \bar{N}_3 = \frac{a_3}{a_{33}}, \bar{N}_4 = 0$$

$$E_4: \quad \bar{N}_1 = 0, \bar{N}_2 = \frac{a_2}{a_{22}}, \bar{N}_3 = 0, \bar{N}_4 = 0$$

$$E_5: \quad \bar{N}_1 = \frac{a_1}{a_{11}}, \bar{N}_2 = 0, \bar{N}_3 = 0, \bar{N}_4 = 0$$

III. States in which two of the four species are washed out while the other two are surviving

$$E_6: \quad \bar{N}_1 = 0, \bar{N}_2 = 0, \bar{N}_3 = \frac{a_4 a_{34} + a_3 a_{44}}{a_{33} a_{44} - a_{34} a_{43}}, \bar{N}_4 = \frac{a_3 a_{43} + a_4 a_{33}}{a_{33} a_{44} - a_{34} a_{43}}$$

This state exists only when $a_{33} a_{44} - a_{34} a_{43} > 0$

$$E_7: \quad \bar{N}_1 = 0, \bar{N}_2 = \frac{a_2}{a_{22}}, \bar{N}_3 = 0, \bar{N}_4 = \frac{a_4}{a_{44}}$$

$$E_8: \quad \bar{N}_1 = 0, \bar{N}_2 = \frac{a_3}{a_{22}} \frac{a_{23}}{a_{33}} + \frac{a_2}{a_{22}}, \bar{N}_3 = \frac{a_3}{a_{33}}, \bar{N}_4 = 0$$

$$E_9: \quad \bar{N}_1 = \frac{a_1}{a_{11}}, \bar{N}_2 = 0, \bar{N}_3 = 0, \bar{N}_4 = \frac{a_4}{a_{44}}$$

$$E_{10}: \quad \bar{N}_1 = \frac{a_1}{a_{11}}, \bar{N}_2 = 0, \bar{N}_3 = \frac{a_3}{a_{33}}, \bar{N}_4 = 0$$



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$$E_{11}: \quad \bar{N}_1 = \frac{a_1 a_{22} - a_2 a_{12}}{a_{11} a_{22} + a_{12} a_{21}}, \bar{N}_2 = \frac{a_1 a_{21} + a_2 a_{11}}{a_{11} a_{22} + a_{12} a_{21}}, \bar{N}_3 = 0, \bar{N}_4 = 0$$

This state exists only when $a_1 a_{22} - a_2 a_{12} > 0$

IV. States in which one of the four species is washed out while the other three are surviving

$$E_{12}: \quad \bar{N}_1 = 0, \bar{N}_2 = \frac{a_{23}(a_4 a_{34} + a_3 a_{44})}{a_{22}(a_{33} a_{44} - a_{34} a_{43})} + \frac{a_2}{a_{22}}, \bar{N}_3 = \frac{a_4 a_{34} + a_3 a_{44}}{a_{33} a_{44} - a_{34} a_{43}},$$

$$\bar{N}_4 = \frac{a_4 a_{33} + a_3 a_{43}}{a_{33} a_{44} - a_{34} a_{43}}$$

This state exists only when $a_{33} a_{44} - a_{34} a_{43} > 0$

$$E_{13}: \quad \bar{N}_1 = \frac{a_1}{a_{11}}, \bar{N}_2 = 0, \bar{N}_3 = \frac{a_4 a_{34} + a_3 a_{44}}{a_{33} a_{44} - a_{34} a_{43}}, \bar{N}_4 = \frac{a_4 a_{33} + a_3 a_{43}}{a_{33} a_{44} - a_{34} a_{43}}$$

This state exists only when $(a_{33} a_{44} - a_{34} a_{43}) > 0$

$$E_{14}: \quad \bar{N}_1 = \frac{a_1 a_{22} - a_2 a_{12}}{a_{11} a_{22} + a_{12} a_{21}}, \bar{N}_2 = \frac{a_1 a_{21} + a_2 a_{11}}{a_{11} a_{22} + a_{12} a_{21}}, \bar{N}_3 = 0, \bar{N}_4 = \frac{a_4}{a_{44}}$$

This state exists only when $a_1 a_{22} - a_2 a_{12} > 0$

$$E_{15}: \quad \bar{N}_1 = \frac{\beta_4}{\beta_1}, \bar{N}_2 = \frac{\beta_5}{\beta_1}, \bar{N}_3 = \frac{a_3}{a_{33}}, \bar{N}_4 = 0$$

Where

$$\beta_1 = a_{33}(a_{11} a_{22} + a_{12} a_{21}), \beta_4 = a_{33}(a_1 a_{22} - a_2 a_{12}) - a_3 a_{23} a_{12}$$

$$\beta_5 = a_{33}(a_1 a_{21} + a_2 a_{11}) + a_3 a_{23} a_{11}$$

This state exists only when $\beta_4 > 0$

V. The co-existent state (or) Normal steady state

$$E_{16}: \quad \bar{N}_1 = \frac{\gamma_1 + a_{12} a_{23} \gamma_2}{\gamma_3 (a_{33} a_{44} - a_{34} a_{43})}, \bar{N}_2 = \frac{\gamma_4 + a_{11} a_{23} \gamma_2}{\gamma_3 (a_{33} a_{44} - a_{34} a_{43})},$$

$$\bar{N}_3 = \frac{a_4 a_{34} + a_3 a_{44}}{a_{33} a_{44} - a_{34} a_{43}}, \bar{N}_4 = \frac{a_4 a_{33} + a_3 a_{43}}{a_{33} a_{44} - a_{34} a_{43}}$$

Where

$$\gamma_1 = (a_1 a_{22} + a_2 a_{12})(a_{33} a_{44} - a_{34} a_{43}), \gamma_2 = a_3 a_{44} + a_4 a_{34}$$

$$\gamma_3 = a_{11} a_{22} + a_{12} a_{21}, \gamma_4 = (a_1 a_{21} - a_2 a_{11})(a_{33} a_{44} - a_{34} a_{43})$$

This state exists only when $(a_1 a_{21} - a_2 a_{11}) > 0$ and $(a_{33} a_{44} - a_{34} a_{43}) > 0$.

The present paper deals with one of the four species are washed out states only. The stability of the other equilibrium states will be presented in the forth coming communications.

IV. STABILITY OF ONE OF THE FOUR SPECIES WASHED OUT EQUILIBRIUM STATES:

V. (SL. NOS 12,13,14,15 IN THE ABOVE EQUILIBRIUM STATES)

A. Stability of the Equilibrium State E_{12} :

Let us consider small deviations $u_1(t), u_2(t), u_3(t), u_4(t)$ from the steady state i.e.

$$N_i(t) = \bar{N}_i + u_i(t), \quad i = 1, 2, 3, 4 \quad \text{--- (4.1.1)}$$



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Substituting (4.1.1) in (2.1), (2.2), (2.3), (2.4) and neglecting products and higher powers of u_1, u_2, u_3, u_4 , we get

$$\frac{du_1}{dt} = w_1 u_1 \quad \dots (4.1.2)$$

$$\frac{du_2}{dt} = a_{21} \bar{N}_2 u_1 - w_3 u_2 + a_{23} \bar{N}_2 u_3 \quad \dots (4.1.3)$$

$$\frac{du_3}{dt} = -a_{33} \bar{N}_3 u_3 + a_{34} \bar{N}_3 u_4 \quad \dots (4.1.4) \quad \frac{du_4}{dt} = a_{43} \bar{N}_4 u_3 - a_{44} \bar{N}_4 u_4 \quad \dots (4.1.5)$$

$$\text{Here } w_1 = a_1 - a_{12} \bar{N}_2, w_3 = a_2 + a_{23} \bar{N}_3 \quad \dots (4.1.6)$$

The characteristic equation of which is

$$(\lambda - w_1)(\lambda + w_3) \left[\lambda^2 + (a_{33} \bar{N}_3 + a_{44} \bar{N}_4) \lambda + (a_{33} a_{44} - a_{34} a_{43}) \bar{N}_3 \bar{N}_4 \right] = 0 \quad \dots (4.1.7)$$

The characteristic roots of (4.1.6) are

$$\lambda = w_1, \lambda = -w_3, \lambda = \frac{-(a_{33} \bar{N}_3 + a_{44} \bar{N}_4) \pm \sqrt{(a_{33} \bar{N}_3 - a_{44} \bar{N}_4)^2 + 4a_{34} a_{43} \bar{N}_3 \bar{N}_4}}{2}$$

Case (A): If $w_1 < 0$ [i.e. $a_1 < a_{12} \bar{N}_2$]

Here $w_1, -w_3$ are negative and the other two roots are also negative.

Hence the equilibrium state is **stable**.

The solutions of the equations (4.1.2), (4.1.3), (4.1.4), (4.1.5) are

$$u_1 = u_{10} e^{w_1 t} \quad \dots (4.1.8)$$

$$u_2 = \left[u_{20} - \frac{a_{21} \bar{N}_2 u_{10}}{(w_1 + w_3)} - \frac{a_{23} \bar{N}_2 (P_1 + P_2)}{(\lambda_3 + w_3)} \right] e^{-w_3 t} + \frac{a_{21} \bar{N}_2 u_{10}}{(w_1 + w_3)} e^{w_1 t} + \frac{a_{23} \bar{N}_2 (P_1 e^{\lambda_3 t} + P_2 e^{\lambda_4 t})}{(\lambda_3 + w_3)} \quad \dots (4.1.9)$$

$$u_3 = \left[\frac{u_{30} (\lambda_3 + a_{44} \bar{N}_4) + u_{40} a_{34} \bar{N}_3}{\lambda_3 - \lambda_4} \right] e^{\lambda_3 t} + \left[\frac{u_{30} (\lambda_4 + a_{44} \bar{N}_4) + u_{40} a_{34} \bar{N}_3}{\lambda_4 - \lambda_3} \right] e^{\lambda_4 t} \quad \dots (4.1.10)$$

$$u_4 = \left[\frac{u_{40} (\lambda_3 + a_{33} \bar{N}_3) + u_{30} a_{43} \bar{N}_4}{\lambda_3 - \lambda_4} \right] e^{\lambda_3 t} + \left[\frac{u_{40} (\lambda_4 + a_{33} \bar{N}_3) + u_{30} a_{43} \bar{N}_4}{\lambda_4 - \lambda_3} \right] e^{\lambda_4 t} \quad \dots (4.1.11)$$

$$\text{Where } P_1 = \frac{u_{30} (\lambda_3 + a_{44} \bar{N}_4) + u_{40} a_{34} \bar{N}_3}{\lambda_3 - \lambda_4}, P_2 = \frac{u_{30} (\lambda_4 + a_{44} \bar{N}_4) + u_{40} a_{34} \bar{N}_3}{\lambda_4 - \lambda_3}$$

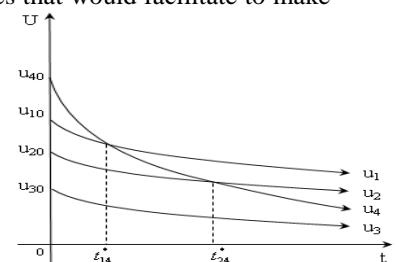
Where $u_{10}, u_{20}, u_{30}, u_{40}$ are the initial values of u_1, u_2, u_3, u_4 respectively.

There would arise in all 576 cases depending upon the ordering of the magnitudes of the growth rates a_1, a_2, a_3, a_4 and the initial values of the perturbations $u_{10}(t), u_{20}(t), u_{30}(t), u_{40}(t)$ of the species S_1, S_2, S_3, S_4 . Of these 576 situations some typical variations are illustrated through respective solution curves that would facilitate to make some reasonable observations.

The solutions are illustrated in figures.

Case (i): If $u_{30} < u_{20} < u_{10} < u_{40}$ and $a_3 < a_1 < a_2 < a_4$

In this case initially S_4 dominates the Prey (S_1) and the Predator (S_2) till the time instant t_{14}^*, t_{24}^* respectively and thereafter the dominance is reversed. And u_1, u_2, u_3, u_4 are converging asymptotically to the equilibrium point. Hence the equilibrium point is **stable**.





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Case (ii): If $u_{40} < u_{10} < u_{30} < u_{20}$ and $A_2 < a_3 < a_1 < a_4$

In this case initially the Predator (S_2) dominates the Prey (S_1) till the time instant t_{12}^* and thereafter the dominance is reversed. Also the host (S_3) of S_2 dominates the Prey (S_1) and S_4 till the time instant t_{13}^* , t_{43}^* respectively and the dominance gets reversed thereafter.

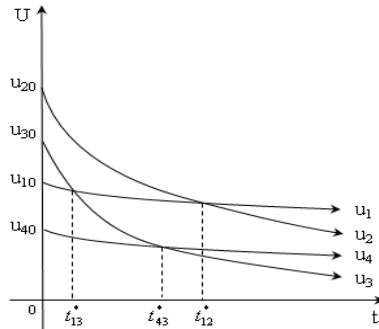


Fig. 2

Case (B): If $w_1 > 0$ [i.e. $a_1 > a_{12} \bar{N}_2$]

Here the root w_1 is positive and the other three roots are negative.

Hence the equilibrium state is **unstable** and the solutions in this case are same as in Case (A).

The solutions are illustrated in figures.

Case (i): If $u_{30} < u_{40} < u_{20} < u_{10}$ and $a_1 < a_4 < A_2 < a_3$

In this case initially S_4 dominates the host (S_3) of S_2 , the Prey (S_1) and the Predator (S_2) in natural growth rate as well as in its initial population strength.

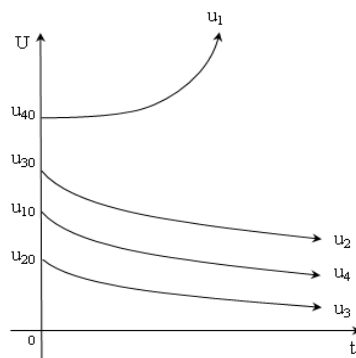
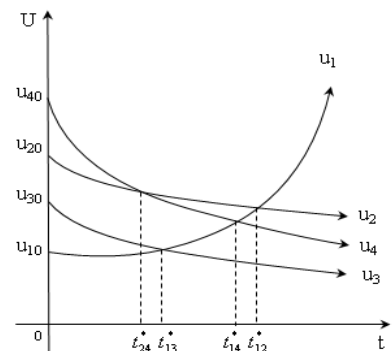


Fig. 3

Case (ii): If $u_{10} < u_{30} < u_{20} < u_{40}$ and $a_1 < a_3 < a_4 < A_2$

In this case initially S_4 dominates the Predator (S_2) and the Prey (S_1) till the time instant t_{24}^* , t_{14}^* respectively and thereafter the dominance is reversed. Also the host (S_3) of S_2 dominates the Prey (S_1) till the time instant t_{13}^* and the dominance gets reversed thereafter. And the

Predator (S_2) dominates the Prey (S_1) till the time instant t_{13}^* and the dominance gets reversed thereafter.





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B. Stability of the Equilibrium State E_{13} :

Substituting (4.1.1) in (2.1), (2.2), (2.3), (2.4) and neglecting products and higher powers of u_1, u_2, u_3, u_4 , we get

$$\frac{du_1}{dt} = -a_1 u_1 - a_{12} \bar{N}_1 u_2 \quad \dots (4.2.1) \quad \frac{du_2}{dt} = g_2 u_2 \quad \dots (4.2.2)$$

$$\frac{du_3}{dt} = -a_{33} \bar{N}_3 u_3 + a_{34} \bar{N}_3 u_4 \quad \dots (4.2.3) \quad \frac{du_4}{dt} = a_{43} \bar{N}_4 u_3 - a_{44} \bar{N}_4 u_4 \quad \dots (4.2.4)$$

$$\text{Here } g_2 = a_2 + a_{21} \bar{N}_1 + a_{23} \bar{N}_3 \quad \dots (4.2.5)$$

The characteristic equation of which is

$$(\lambda_1 + a_1)(\lambda - g_2) \left[\lambda^2 + (a_{33} \bar{N}_3 + a_{44} \bar{N}_4) \lambda + (a_{33} a_{44} - a_{34} a_{43}) \bar{N}_3 \bar{N}_4 \right] = 0 \quad \dots (4.2.6)$$

The characteristic roots of (4.2.6) are

$$\lambda = -a_1, \lambda = g_2, \lambda = \frac{-(a_{33} \bar{N}_3 + a_{44} \bar{N}_4) \pm \sqrt{(a_{33} \bar{N}_3 - a_{44} \bar{N}_4)^2 + 4a_{34} a_{43} \bar{N}_3 \bar{N}_4}}{2}$$

One root of the characteristic equation $\lambda = r_2$ is positive and the remaining three roots are negative. Hence the equilibrium state is unstable and the solutions are

$$u_1 = \left(u_{10} + \frac{a_{12} a_1 u_{20}}{a_{11}(g_2 + a_1)} \right) e^{-a_1 t} - \frac{a_{12} a_1 u_{20}}{a_{11}(g_2 + a_1)} e^{g_2 t} \quad \dots (4.6.7)$$

$$u_2 = u_{20} e^{g_2 t} \quad \dots (4.6.8)$$

$$u_3 = p_1 e^{\lambda_3 t} + p_2 e^{\lambda_4 t} \quad \dots (4.6.9)$$

$$u_4 = \left[\frac{u_{40} (\lambda_3 + a_{33} \bar{N}_3) + u_{30} a_{43} \bar{N}_4}{\lambda_3 - \lambda_4} \right] e^{\lambda_3 t} + \left[\frac{u_{40} (\lambda_4 + a_{33} \bar{N}_3) + u_{30} a_{43} \bar{N}_4}{\lambda_4 - \lambda_3} \right] e^{\lambda_4 t} \quad \dots (4.6.10)$$

Where

$$p_1 = \frac{u_{30} (\lambda_3 + a_{44} \bar{N}_4) + u_{40} a_{34} \bar{N}_3}{\lambda_3 - \lambda_4}, p_2 = \frac{u_{30} (\lambda_4 + a_{44} \bar{N}_4) + u_{40} a_{34} \bar{N}_3}{\lambda_4 - \lambda_3}$$

The solutions are illustrated in figures.

Case (i): If $u_{40} < u_{20} < u_{10} < u_{30}$ and $a_4 < a_3 < a_1 < g_2$

In this case initially the host (S_3) of S_2 dominates the Prey (S_1) till the time instant t_{23}^* and the dominance gets reversed thereafter. Also the Prey (S_1) dominates the Predator (S_2) till the time instant t_{21}^* and thereafter the dominance is reversed.

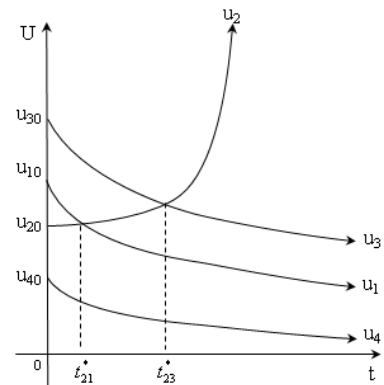


Fig. 5



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Case (ii): If $u_{10} < u_{20} < u_{40} < u_{30}$ and $g_2 < a_1 < a_4 < a_3$

In this case initially the host (S_3) of S_2 dominates the Predator (S_2) till the time instant t_{23}^* and thereafter the dominance is reversed. Also S_4 dominates the Predator (S_2) till the time instant t_{24}^* and the dominance gets reversed thereafter.

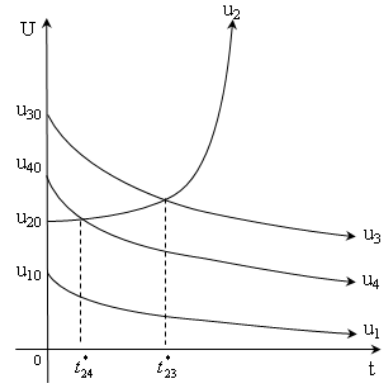


Fig. 6

C. Stability of the Equilibrium State E_{14} :

Substituting (4.1.1) in (2.1), (2.2), (2.3), (2.4) and neglecting products and higher powers of u_1, u_2, u_3, u_4 , we get

$$\frac{du_1}{dt} = -a_{11}\bar{N}_1u_1 - a_{12}\bar{N}_1u_2 \quad \dots (4.3.1)$$

$$\frac{du_2}{dt} = (a_2 - 2a_{22}\bar{N}_2 + a_{21}\bar{N}_1)u_2 + a_{21}\bar{N}_2u_1 + a_{23}\bar{N}_2u_3 \quad \dots (4.3.2)$$

$$\frac{du_3}{dt} = l_3u_3 \quad \dots (4.3.3) \quad \frac{du_4}{dt} = -a_4u_4 + a_{43}\frac{a_4}{a_{44}}u_3 \quad \dots (4.3.4)$$

$$\text{Here } l_3 = a_3 + a_{34}\frac{a_4}{a_{44}} \quad \dots (4.3.5)$$

The characteristic equation of which is

$$(\lambda - l_3)(\lambda + a_4) \left[\lambda^2 - (M_3 - a_{11}\bar{N}_1)\lambda + [(-a_{11}\bar{N}_1)(M_3) + a_{12}a_{21}\bar{N}_1\bar{N}_2] \right] = 0 \quad \dots (4.3.6)$$

The characteristic roots of (4.3.6) are

$$\lambda = l_3, \lambda = -a_4, \lambda = \frac{(M_3 - a_{11}\bar{N}_1) \pm \sqrt{(M_3 - a_{11}\bar{N}_1)^2 - [a_{12}a_{21}\bar{N}_1\bar{N}_2 - M_3a_{11}\bar{N}_1]}}{2}$$

$$\text{Where } M_3 = a_2 - 2a_{22}\bar{N}_2 + a_{21}\bar{N}_1$$

One root of the characteristic equation $\lambda = l_3$ is positive and the remaining three roots are negative. Hence the equilibrium state is unstable and the solutions are

$$u_1 = \left\{ \frac{(u_{10} + u_{20})a_{12}\bar{N}_1 - \phi_3(\lambda_2 - l_3)}{\lambda_2 - \lambda_1} \right\} e^{\lambda_1 t} + \left\{ \frac{(u_{10} - \phi_3)(\lambda_2 - \lambda_1) - (u_{10} + u_{20})a_{12}\bar{N}_1 + \phi_3(\lambda_2 - l_3)}{\lambda_2 - \lambda_1} \right\} e^{\lambda_2 t} + \phi_3 e^{l_3 t} \quad \dots (4.3.7)$$



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$$u_2 = \left\{ \frac{(u_{10} + u_{20})a_{12}\bar{N}_1 - \phi_3(\lambda_2 - l_3)}{\lambda_2 - \lambda_1} \right\} e^{\lambda_1 t} \xi_1 \dots (4.3.8)$$

$$+ \left\{ \frac{(u_{10} - \phi_3)(\lambda_2 - \lambda_1) - (u_{10} + u_{20})a_{12}\bar{N}_1 + \phi_3(\lambda_2 - l_3)}{\lambda_2 - \lambda_1} \right\} e^{\lambda_2 t} \xi_2 + \phi_4 e^{l_3 t}$$

$$u_3 = u_{30} e^{l_3 t} \dots (4.3.9)$$

$$u_4 = \left[u_{40} - \frac{a_4 a_{43} u_{30}}{a_{44}(l_3 + a_4)} \right] e^{-a_4 t} + \frac{a_4 a_{43} u_{30}}{a_{44}(l_3 + a_4)} e^{l_3 t} \dots (4.3.10)$$

Where

$$\phi_3 = \frac{\beta_4}{l_3^2 + \psi_2 l_3 + \beta_3}, \psi_2 = a_{11}\bar{N}_1 - a_{21}\bar{N}_1 + 2a_{22}\bar{N}_2 - a_2, \phi_4 = \frac{\phi_3(l_3 + p_3)}{a_{12}\bar{N}_1}$$

$$\beta_3 = (2a_{11}a_{22}\bar{N}_2 - a_2 a_{11} - a_{11}a_{21}\bar{N}_1 - a_{12}a_{21}\bar{N}_2)\bar{N}_1, \beta_4 = -a_{12}a_{23}u_{30}\bar{N}_1\bar{N}_2$$

$$\xi_1 = \frac{-(\lambda_1 + p_3)}{a_{12}\bar{N}_1}, \xi_2 = \frac{-(\lambda_2 + p_3)}{a_{12}\bar{N}_1}, p_3 = a_{11}\bar{N}_1$$

The solutions are illustrated in figures.

Case (i): If $u_{30} < u_{20} < u_{40} < u_{10}$ and $l_3 < a_1 < a_2 < a_4$

In this case initially the Prey (S_1) dominates S_4 and the host (S_3) of S_2 till the time instant t_{41}^*, t_{31}^* respectively and thereafter the dominance is reversed. Also S_4 dominates the host (S_3) of S_2 till the time instant t_{34}^* and the dominance gets reversed thereafter. Similarly the Predator (S_2) dominates the host (S_3) of S_2 till the time instant t_{32}^* and thereafter the dominance is reversed.

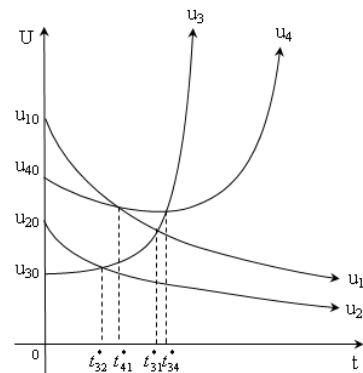


Fig. 7

Case (ii): If $u_{10} < u_{30} < u_{40} < u_{20}$ and $a_4 < a_1 < l_3 < a_2$

In this case initially the Predator (S_2) dominates S_4 , the host (S_3) of S_2 and the Prey (S_1) till the time instant $t_{42}^*, t_{32}^*, t_{12}^*$ respectively and thereafter the dominance is reversed. Also S_4 dominates the host (S_3) of S_2 till the time instant t_{34}^* and the dominance gets reversed thereafter.

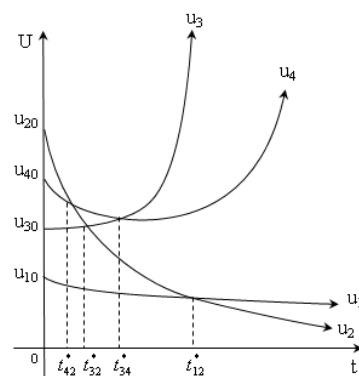


Fig. 8



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D. Stability of the Equilibrium State E_{15} :

Substituting (4.1.1) in (2.1), (2.2), (2.3), (2.4) and neglecting products and higher powers of u_1, u_2, u_3, u_4 , we get

$$\frac{du_1}{dt} = -a_{11}\bar{N}_1u_1 - a_{12}\bar{N}_1u_2 \quad \dots (4.4.1)$$

$$\frac{du_2}{dt} = -a_{22}\bar{N}_2u_2 + a_{21}\bar{N}_2u_1 + a_{23}\bar{N}_2u_3 \quad \dots (4.4.2)$$

$$\frac{du_3}{dt} = -a_3u_3 + a_{34}\bar{N}_3u_4 \quad \dots (4.4.3)$$

$$\frac{du_4}{dt} = n_4u_4 \quad \dots (4.4.4)$$

$$\text{Here } n_4 = a_4 + a_{43} \frac{a_3}{a_{33}} \quad \dots (4.4.5)$$

The characteristic equation of which is

$$\left[\lambda^2 + (a_{11}\bar{N}_1 + a_{22}\bar{N}_2)\lambda + (a_{11}a_{22} + a_{12}a_{21})\bar{N}_1\bar{N}_2 \right] (\lambda - n_4)(\lambda + a_3) = 0 \quad \dots (4.4.6)$$

The characteristic roots of (4.15.6) are

$$\lambda = \frac{-(a_{11}\bar{N}_1 + a_{22}\bar{N}_2) \pm \sqrt{(a_{11}\bar{N}_1 - a_{22}\bar{N}_2)^2 - 4a_{12}a_{21}\bar{N}_1\bar{N}_2}}{2}, \lambda = n_4, \lambda = -a_3$$

One root of the characteristic equation $\lambda = n_4$ is positive and the remaining three roots are negative. Hence the equilibrium state is unstable and the solutions are

$$u_1 = \left\{ \frac{(u_{10} + u_{20} - w_3^* - w_4^*)a_{12}\bar{N}_1 - (\lambda_2 + P_3)(w_3 + w_4)}{\lambda_2 - \lambda_1} \right\} e^{\lambda_1 t} + \left\{ \frac{[u_{10} - (w_3 + w_4)](\lambda_2 - \lambda_1) + (u_{10} + u_{20} - w_3^* - w_4^*)a_{12}\bar{N}_1 - (\lambda_2 + P_3)(w_3 + w_4)}{\lambda_2 - \lambda_1} \right\} e^{\lambda_2 t} + w_3 e^{-a_3 t} + w_4 e^{n_4 t} \quad \dots (4.4.7)$$

$$u_2 = \left\{ \frac{(u_{10} + u_{20} - w_3^* - w_4^*)a_{12}\bar{N}_1 - (\lambda_2 + P_3)(w_3 + w_4)}{\lambda_2 - \lambda_1} \right\} \xi_1 e^{\lambda_1 t} + \left\{ \frac{[u_{10} - (w_3 + w_4)](\lambda_2 - \lambda_1) + (u_{10} + u_{20} - w_3^* - w_4^*)a_{12}\bar{N}_1 - (\lambda_2 + P_3)(w_3 + w_4)}{\lambda_2 - \lambda_1} \right\} \xi_2 e^{\lambda_2 t} + w_3^* e^{-a_3 t} + w_4^* e^{n_4 t} \quad \dots (4.4.8)$$

$$u_3 = \left[u_{30} - \frac{a_3 a_{34} u_{40}}{a_{33}(n_4 + a_3)} \right] e^{-a_3 t} + \frac{a_3 a_{34} u_{40}}{a_{33}(n_4 + a_3)} e^{n_4 t} \quad \dots (4.4.9)$$

$$u_4 = u_{40} e^{n_4 t} \quad \dots (4.4.10)$$

where

$$w_3 = \frac{(u_{30} - r_4)a_{12}a_{23}\bar{N}_1\bar{N}_2}{D^2 - \psi_1 D + \beta_5}, w_4 = \frac{a_{12}a_{23}\bar{N}_1\bar{N}_2}{D^2 - \psi_1 D + \beta_5}, D = -a_3$$

$$w_3^* = w_3(a_3 - P_3), w_4^* = -(n_4 + P_3), \xi_1 = \frac{-(\lambda_1 + p_3)}{a_{12}\bar{N}_1}, \xi_2 = \frac{-(\lambda_2 + p_3)}{a_{12}\bar{N}_1}, p_3 = a_{11}\bar{N}_1$$



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$$\psi_1 = a_{11}\bar{N}_1 + a_{22}\bar{N}_2, \beta_5 = a_{11}a_{22}\bar{N}_1\bar{N}_2 + a_{21}\bar{N}_2, r_4 = \frac{a_3 a_{34} u_{40}}{a_{33}(n_4 + a_3)}$$

The solutions are illustrated in figures.

Case (i): If $u_{30} < u_{40} < u_{10} < u_{20}$ and $n_4 < a_3 < a_2 < n_1$

In this case initially the Predator (S_2) dominates S_4 and the host (S_3) of S_2 till the time instant t_{42}^*, t_{32}^* respectively and thereafter the dominance is reversed. Also the Prey (S_1) dominates S_4 and the host (S_3) of S_2 till the time instant t_{41}^*, t_{31}^* respectively and the dominance gets reversed thereafter.

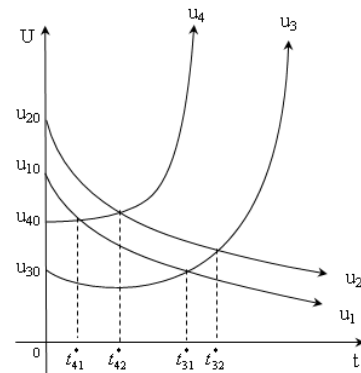


Fig. 9

Case (ii): If $u_{30} < u_{40} < u_{10} < u_{20}$ and $n_4 < a_3 < a_2 < n_1$

In this case initially the host (S_3) of S_2 dominates S_4 till the time instant t_{43}^* and thereafter the dominance is reversed. Also the Predator (S_2) dominates S_4 till the time instant t_{42}^* and the dominance gets reversed thereafter. Similarly the Prey (S_1) dominates S_4 till the time instant t_{41}^* and thereafter the dominance is reversed.

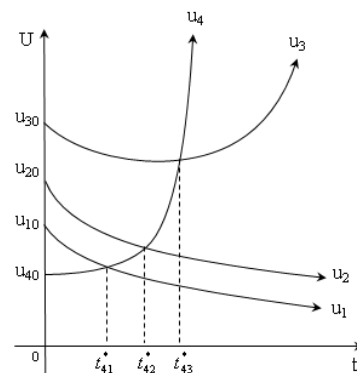


Fig. 10

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